

Entropy Production in Thermostats II

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We show that an arbitrary Anosov Gaussian thermostat close to equilibrium has positive entropy production unless the external field E has a global potential. The configuration space is allowed to have any dimension and magnetic forces are also allowed. We also show the following non-perturbative result. Suppose a Gaussian thermostat satisfies

$$K_w(\sigma) + \frac{1}{4}|E_\sigma|^2 < 0$$

for every 2-plane σ , where K_w is the sectional curvature of the associated Weyl connection and E_σ is the orthogonal projection of E onto σ . Then the entropy production of any SRB measure is positive unless E has a global potential. A related non-perturbative result is also obtained for certain generalized thermostats on surfaces.

KEY WORDS: entropy production, Gaussian thermostat, SRB state, Axiom A flow

1. INTRODUCTION

In this paper we consider the dynamical system given by the motion of a particle of unit mass on a closed Riemannian n -manifold M subject to the action of an external field E . We also enforce as a constraint that the kinetic energy is a constant of motion, so the resulting equation is:

$$\frac{D\dot{\gamma}}{dt} = E(\gamma) - \frac{\langle E(\gamma), \dot{\gamma} \rangle}{|\dot{\gamma}|^2} \dot{\gamma}, \quad (1)$$

where D denotes covariant derivative and $\gamma : \mathbb{R} \rightarrow M$ is a curve in M . This equation defines a flow ϕ on the unit sphere bundle SM of M which reduces to the geodesic flow (free motion) when $E = 0$. The kinetic energy is held fixed by

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Gauss' principle of least constraint and thus the system defined by (1) is referred to as *Gaussian thermostat*. Thermostats have become quite popular as models in nonequilibrium statistical mechanics.^(5,11,14,18,31) Like geodesic flows, they are *reversible*, that is, the flip $SM \ni (x, v) \mapsto (x, -v) \in SM$ conjugates ϕ_t with ϕ_{-t} .

Let \mathbf{G}_E be the vector field in SM that generates ϕ . An easy calculation (cf. Ref. 36) shows that the divergence $\operatorname{div} \mathbf{G}_E$ of \mathbf{G}_E with respect to the canonical volume form Θ of SM is given by

$$\operatorname{div} \mathbf{G}_E = -(n - 1)\theta, \tag{2}$$

where θ is the 1-form dual to E , i.e., $\theta_x(v) = \langle E(x), v \rangle$ and we regard θ also as a function $\theta : TM \rightarrow \mathbb{R}$. We see right away that ϕ does not preserve the Liouville measure (i.e. Θ) unless $E = 0$. But in principle, the flow may preserve other smooth measures. In fact, it is an exercise to check that ϕ preserves a smooth volume form iff θ is a *coboundary*, that is, iff there exists a smooth function $u : SM \rightarrow \mathbb{R}$ which solves the *cohomological equation*

$$\mathbf{G}_E(u) = \theta. \tag{3}$$

For example, suppose θ is an exact 1-form, i.e., the external field E has a global potential U and write $E = -\nabla U$. Then $\mathbf{G}_E(-U \circ \pi) = \theta$, where $\pi : SM \rightarrow M$ is footpoint projection: $\pi(x, v) = x$. However, in general, one does not expect to have smooth solutions of (3). For example, if θ is a closed, non-exact 1-form and every homology class in $H_1(SM, \mathbb{Z})$ contains a closed orbit of ϕ , then there is no global solution to (3).³

In the presence of hyperbolicity, there is a close relationship between (3) and the *entropy production* of an SRB state ρ which we now describe. We will say that a ϕ -invariant measure ρ is an SRB measure (or state) if ρ is ergodic and

$$h_\rho(\phi) = \sum \text{positive Lyapunov exponents},$$

where $h_\rho(\phi)$ is the measure theoretic entropy of ϕ with respect to ρ . The entropy production of the state ρ is given by (cf. Ref. 29)

$$e_\phi(\rho) := - \int \operatorname{div} \mathbf{G}_E d\rho = - \sum \text{Lyapunov exponents}.$$

D. Ruelle⁽²⁹⁾ observed that $e_\phi(\rho) \geq 0$ with equality iff

$$\begin{aligned} h_\rho(\phi) &= \sum \text{positive Lyapunov exponents} \\ &= - \sum \text{negative Lyapunov exponents}. \end{aligned} \tag{4}$$

³Note that $\pi^* : H^1(M, \mathbb{R}) \rightarrow H^1(SM, \mathbb{R})$ is an isomorphism for M different from the 2-torus, thus θ is exact iff $\pi^*\theta$ is exact.

Suppose now that ϕ is an Axiom A flow (we recall the definition in Sec. 3) and let ρ be an SRB state. We will see in Lemma 3.1 that if $e_\phi(\rho) = 0$, then ϕ is in fact a transitive Anosov flow and (3) must hold. Conversely if (3) holds, then ϕ preserves a smooth measure and ϕ is a transitive Anosov flow. Hence ρ must be the unique invariant smooth measure and consequently (4) holds which in turn implies $e_\phi(\rho) = 0$.

Thus, for Axiom A thermostats, $e_\phi(\rho) = 0$ iff there exists a smooth solution of (3).

In Sec. 5 we will explain why a transitive Anosov thermostat is always *homologically full*, i.e. every homology class in $H_1(SM, \mathbb{Z})$ contains a closed orbit. Thus, if θ is closed, but not exact (e.g. electromotive forces), then $e_\rho(\phi) > 0$ for any Axiom A thermostat. This was proved by M. Wojtkowski [Ref. 36, Proposition 3.1] assuming that ϕ is an Anosov flow topologically conjugate to a geodesic flow, and by F. Bonetto, G. Gentile and V. Mastropietro⁽¹⁾ for the case of a metric of constant negative curvature and θ a small harmonic 1-form.

The natural question now is: what happens for an arbitrary field E which does not necessarily have local potentials? In two degrees of freedom the problem was solved completely in Ref. 6: an Anosov Gaussian thermostat has zero entropy production iff E has a global potential. The aim of the present paper is to provide similar results for n degrees of freedom.

We note that the assumption that ϕ is uniformly hyperbolic is known in the literature on nonequilibrium statistical mechanics as the *chaotic hypothesis* of G. Gallavotti and E.G.D. Cohen: for systems out of equilibrium, physically correct macroscopic results will be obtained by assuming that the microscopic dynamics is uniformly hyperbolic. A system with $e_\phi(\rho) > 0$ is sometimes referred to as *dissipative*. Dissipative Gaussian thermostats provide a large class of examples to which one can apply the Fluctuation Theorem of Gallavotti and Cohen^(10,12,13) (extended to Anosov flows by G. Gentile⁽¹⁵⁾) and this theorem is perhaps one of the main motivations for determining precisely which thermostats are dissipative.

In our first result we will allow magnetic forces. This involves the addition of a Lorentz force \mathbf{F} to the right hand side of (1). For each $x \in M$, $\mathbf{F}_x : T_x M \rightarrow T_x M$ is an antisymmetric linear map such that the 2-form $\langle \mathbf{F}_x(v), w \rangle$ is closed. We will indicate this thermostat by $\phi_{E, \mathbf{F}}$. Note that $\phi_{0, \mathbf{F}}$ is a magnetic flow and hence it preserves the volume form Θ . Suppose $\phi_{0, \mathbf{F}}$ is Anosov and E is an arbitrary external field. Then for ε sufficiently small and $s \in (-\varepsilon, \varepsilon)$, the flow $\phi_{sE, \mathbf{F}}$ is also a transitive Anosov flow. Moreover, the map $(-\varepsilon, \varepsilon) \ni s \mapsto e(s) := e_{\phi_{sE, \mathbf{F}}}(\rho_s)$ is smooth.^(3,30,32) It is immediate that $e'(0) = 0$ and in Sec. 2 we will show that $e''(0) \geq 0$ with equality iff E has a global potential. Thus we obtain:

Theorem A. *An Anosov Gaussian thermostat close to equilibrium has zero entropy production if and only if the external field E has a global potential. Magnetic forces are allowed at equilibrium.*

We now explain the non-perturbative results (which do not include magnetic forces). Given a 2-plane $\sigma \subset T_x M$, set:

$$k(\sigma) := K(\sigma) - \operatorname{div}_\sigma E - |E|^2 + \frac{5}{4}|E_\sigma|^2, \tag{5}$$

where $K(\sigma)$ is the sectional curvature of the 2-plane σ , E_σ is the orthogonal projection of E onto σ and $\operatorname{div}_\sigma E := \langle \nabla_\xi E, \xi \rangle + \langle \nabla_\eta E, \eta \rangle$ for any orthonormal basis $\{\xi, \eta\}$ of σ . The expression

$$K_w(\sigma) := K(\sigma) - \operatorname{div}_\sigma E - |E|^2 + |E_\sigma|^2,$$

is precisely the sectional curvature of the Weyl connection:⁽³⁷⁾

$$\nabla_X^w Y = \nabla_X Y + \langle X, E \rangle Y + \langle Y, E \rangle X - \langle X, Y \rangle E.$$

Hence

$$k(\sigma) = K_w(\sigma) + \frac{1}{4}|E_\sigma|^2.$$

Theorem B. *Let ϕ be a Gaussian thermostat with $k < 0$ and let ρ be an SRB measure. Then $e_\rho(\phi) = 0$ if and only if the external field E has a global potential.*

Like in Ref. 6 this non-perturbative result will be established by using Pestov type identities as in Refs. 4,8 for geodesic flows. A closely related result about the cohomological equation $\mathbf{G}_E(u) = \vartheta$, where ϑ is an arbitrary 1-form is presented in Theorem 4.3.

We remark that in [Ref. 37, Theorem 5.1], M. Wojtkowski has shown that for $n \geq 3$, the condition $k < 0$ implies that ϕ is Anosov and for $n = 2$ it suffices to assume that $K_w < 0$. (In general, $K_w < 0$ only ensures that the flow has a dominated splitting).

Our last non-perturbative result concerns a more general class of thermostats, but it will be only for $n = 2$. In principle, nothing impedes us from considering external fields acting on the particle which are also *velocity dependent*. The way to formalize this is to say that our external field is a *semibasic vector field* $E(x, v)$, that is, a smooth map $TM \ni (x, v) \mapsto E(x, v) \in TM$ such that $E(x, v) \in T_x M$ for all $(x, v) \in TM$. As before the equation

$$\frac{D\dot{\gamma}}{dt} = E(\gamma, \dot{\gamma}) - \frac{\langle E(\gamma, \dot{\gamma}), \dot{\gamma} \rangle}{|\dot{\gamma}|^2} \dot{\gamma}.$$

defines a flow ϕ on the unit sphere bundle SM . These generalized thermostats are reversible as long as $E(x, v) = E(x, -v)$.

Suppose now that M is a closed oriented surface. Set $\lambda(x, v) := \langle E(x, v), iv \rangle$, where i indicates rotation by $\pi/2$ according to the orientation of the surface. The

evolution of the thermostat on SM can now be written as

$$\frac{D\dot{\gamma}}{dt} = \lambda(\gamma, \dot{\gamma})i\dot{\gamma}. \tag{6}$$

If λ does not depend on v , then ϕ is the magnetic flow associated with the Lorentz force $\mathbf{F}_x(v) = \lambda(x)iv$. If λ depends linearly on v , we obtain the Gaussian thermostat (1).

If we fix a Riemannian metric on M , its conformal class determines a complex structure. Given a positive integer k , let \mathcal{H}_k denote the space of holomorphic sections of the k -th power of the canonical line bundle. By the Riemann–Roch theorem this space has complex dimension $(2k - 1)(g - 1)$ for $k \geq 2$ and complex dimension g for $k = 1$, where g is the genus of M . (For $k = 1$ we get the holomorphic 1-forms and for $k = 2$ the holomorphic quadratic differentials.) Note that the elements in \mathcal{H}_k can be regarded as functions on SM .⁴

Recall that $\pi : SM \rightarrow M$ is a principal S^1 -fibration and we let V be the infinitesimal generator of the action of S^1 . If \mathbf{G} denotes the vector field that generates the geodesic flow, the horizontal vector field H is given by the Lie bracket $H = [V, \mathbf{G}]$.

Theorem C. *Let M be a closed oriented surface and consider an Anosov generalized thermostat (6) determined by $\lambda = \Re(q)$, where $q \in \mathcal{H}_k$. Suppose*

$$K - H(\lambda) + \lambda^2[(k + 1)^2/(2k + 1)] \leq 0,$$

where K is the Gaussian curvature of M . Then ϕ has zero entropy production if and only if $\lambda = 0$.

When $K = -1$, $k = 1$, and λ is sufficiently small, the theorem is proved in Ref. 1 using the same perturbative methods as we will use for the proof of Theorem A. Note that for k odd the flow ϕ is reversible, so Theorem C provides a large class of new examples to which the Fluctuation Theorem of Gallavotti and Cohen applies.

2. DERIVATIVES OF ENTROPY PRODUCTION

2.1. The Variance

Let ϕ be a transitive Anosov flow on a closed manifold X . We will assume that ϕ is weak-mixing, i.e., the equation $F \circ \phi_t = e^{iat}F$, $a > 0$, has no continuous solutions.

⁴ Sections of the k -th power of the canonical line bundle can be regarded as functions on SM which transform according to the rule $f(x, e^{i\varphi}v) = e^{ik\varphi}f(x, v)$.

Let μ be a Gibbs state associated with some Hölder continuous potential. Given a Hölder continuous function $F : X \rightarrow \mathbb{R}$, the *variance* of F with respect to μ is defined as:

$$\text{Var}_\mu(F) := \lim_{T \rightarrow \infty} \frac{1}{T} \int_X \left(\int_0^T (F \circ \phi_t - \bar{F}) dt \right)^2 d\mu,$$

where

$$\bar{F} := \int_X F d\mu.$$

This limit exists and it appears in the central limit theorem for hyperbolic flows.⁽²⁷⁾ There are other equivalent ways of expressing the variance. Let

$$\rho_F(t) := \int_X (F \circ \phi_t \cdot F - \bar{F}^2) d\mu$$

be the auto-correlation function of F . Then the variance can also be expressed as (cf. Ref. 26, Sec. 4):

$$\text{Var}_\mu(F) = \int_{-\infty}^{\infty} \rho_F(t) dt = 2 \int_0^{\infty} \rho_F(t) dt.$$

In fact the Fourier transform of ρ_F

$$\hat{\rho}_F^+(w) := \int_0^{\infty} e^{iwt} \rho_F(t) dt$$

defined as a distribution, has a meromorphic extension to a strip $|\Im(w)| \leq \varepsilon$ with no pole at $w = 0$.^(28,25) The value at $w = 0$ is precisely $\text{Var}_\mu(F)/2$.

2.2. Proof of Theorem A

We first recall the setting described in the introduction. Consider a closed Riemannian manifold and \mathbf{F} a Lorentz force. Suppose $\phi_{0,\mathbf{F}}$ is Anosov and E is an arbitrary external field. Then, by structural stability, for ε sufficiently small and $s \in (-\varepsilon, \varepsilon)$, the flow $\phi_{sE,\mathbf{F}}$ is also a transitive (and weak-mixing) Anosov flow.

Consider the map

$$(-\varepsilon, \varepsilon) \ni s \mapsto e(s) := e_{\phi_{sE,\mathbf{F}}}(\rho_s).$$

It follows from the results of G. Contreras⁽³⁾ or Ruelle^(30,32) that this map is smooth. Indeed since $\text{div } \mathbf{G}_{sE,\mathbf{F}} = -(n-1)s\theta$, we have

$$e(s) = (n-1)s \int_{SM} \theta d\rho_s$$

and the results in Refs. 30,32 assert that $s \mapsto \int_{SM} \theta \, d\rho_s$ is smooth. Thus

$$e'(0) = (n - 1) \int_{SM} \theta \, d\mu,$$

$$e''(0) = 2(n - 1) \left. \frac{d}{ds} \right|_{s=0} \int_{SM} \theta \, d\rho_s.$$

Here $\mu := \rho_0$ is the Liouville measure of SM . We see right away that $e'(0) = 0$ since

$$\int_{SM} \theta \, d\mu = 0$$

because $\theta_x(v) = -\theta_x(-v)$. The derivative

$$\left. \frac{d}{ds} \right|_{s=0} \int_{SM} \theta \, d\rho_s$$

can be computed from the results in Refs. 30,32. Given a smooth function $F : SM \rightarrow \mathbb{R}$, the derivative

$$\left. \frac{d}{ds} \right|_{s=0} \int_{SM} F \, d\rho_s$$

is the limit as $\omega \rightarrow 0$ with $\Im(w) > 0$ of

$$\int_0^\infty e^{iwt} \int_{SM} d(F \circ \phi_t)_{(x,v)}(Y(x, v)) \, d\mu(x, v)$$

$$= - \int_0^\infty e^{iwt} \int_{SM} \operatorname{div} Y(x, v) F(\phi_t(x, v)) \, d\mu(x, v)$$

where Y is such that $\mathbf{G}_{sE, \mathbf{F}} = \mathbf{G}_{0, \mathbf{F}} + s Y$. Since $\operatorname{div}(\mathbf{G}_{sE, \mathbf{F}} - \mathbf{G}_{0, \mathbf{F}}) = -s(n - 1)\theta$ we see that

$$e''(0) = 2(n - 1)^2 \lim_{w \rightarrow 0} \int_0^\infty e^{iwt} \int_{SM} \theta_x(v) \theta(\phi_t(x, v)) \, d\mu(x, v).$$

As pointed out before

$$\omega \mapsto \int_0^\infty e^{iwt} \int_{SM} \theta_x(v) \theta(\phi_t(x, v)) \, d\mu(x, v)$$

extends to a holomorphic function near $w = 0$. We can now identify

$$2 \lim_{w \rightarrow 0} \int_0^\infty e^{iwt} \int_{SM} \theta_x(v) \theta(\phi_t(x, v)) \, d\mu(x, v)$$

with the variance of the function θ with respect to the Liouville measure μ . Thus

$$e''(0) = (n - 1)^2 \operatorname{Var}_\mu(\theta).$$

The variance has the wonderful property that $\text{Var}_\mu(F) \geq 0$ with equality iff F is a coboundary [Ref. 26, Sec. 4]. Thus we have shown that $e'(0) = 0$ and $e''(0) \geq 0$ with equality iff there exists a smooth solution u to the cohomological equation

$$\mathbf{G}_{0,\mathbf{F}}(u) = \theta. \tag{7}$$

But the results in [Ref. 7, Theorem B] give a complete understanding of the cohomological equation for Anosov magnetic flows. Indeed, there is a solution of (7) iff θ is an exact form. For geodesic flows (i.e. $\mathbf{F} = 0$) this result is proved in Ref. 8.

Thus, unless E has a global potential, $e''(0) > 0$ and therefore $e(s)$ is strictly positive for $s \neq 0$ near zero. This shows Theorem A.

2.3. Some Explicit Calculations of $\text{Var}_\mu(\theta)$

Suppose M is a compact locally symmetric space of negative curvature and suppose θ is a harmonic 1-form. If $\mathbf{F} = 0$, then $\text{Var}_\mu(\theta)$ has been calculated by A. Katsuda and T. Sunada in [Ref. 20, Proposition 1.3]. They show that

$$\text{Var}_\mu(\theta) = \frac{2}{h \text{Vol}(M)} \int_M |\theta|^2$$

where h is the topological entropy of the geodesic flow of M . For $n = 2$ and $h = 1$ ($K = -1$) we obtain

$$e''(0) = \frac{2}{\text{Vol}(M)} \int_M |\theta|^2.$$

With an appropriate normalization for the L^2 -norm of θ we recover precisely the calculation performed in [Ref. 1, Page 687] to compute $e''(0)$.

It is interesting to see what happens for $n = 2$ and $K = -1$ if one adds a uniform magnetic field. Suppose we take $\mathbf{F}_x(v) = iv$ and $\lambda \in [0, \infty)$. It is well known that for $0 \leq \lambda < 1$, the flow $\phi_{0,\lambda\mathbf{F}}$ is Anosov and for $\lambda = 1$ we obtain the horocycle flow. Let θ be a harmonic 1-form and for $\lambda \in [0, 1)$ let us try to compute $\text{Var}_{\lambda,\mu}(\theta)$, the variance of θ with respect the flow $\phi_{0,\lambda\mathbf{F}}$ and the Liouville measure μ . A direct calculation along the lines in Ref. 1 is possible, but we will take a different, more economical approach that exploits the good properties of the variance. It is also well known (see for example Ref. 22) that the flow $\phi_{0,\lambda\mathbf{F}}$ is conjugate to the geodesic flow $\phi_{0,0}$, up to a constant time scaling by $\sqrt{1 - \lambda^2}$. Let $f = f_\lambda : SM \rightarrow SM$ be this conjugacy and note that it is immediate to check that f_0 is the identity, so f is isotopic to the identity. Since f is a conjugacy:

$$df_{(x,v)}(\mathbf{X}_\lambda) = \mathbf{G}_{0,\lambda\mathbf{F}}(f(x, v)),$$

where $\mathbf{X}_\lambda = \sqrt{1 - \lambda^2} \mathbf{G}_{0,0}$. Observe that $\theta_x(v) = \pi^*\theta(\mathbf{G}_{0,\lambda\mathbf{F}})(x, v)$ and therefore

$$\begin{aligned} \theta \circ f(x, v) &= \pi^*\theta(\mathbf{G}_{0,\lambda\mathbf{F}})(f(x, v)) = \pi^*\theta(df_{(x,v)}\mathbf{X}_\lambda) \\ &= f^*\pi^*\theta(\mathbf{X}_\lambda)(x, v). \end{aligned}$$

Hence

$$\text{Var}_{\lambda,\mu}(\theta) = \text{Var}_{\mathbf{X}_\lambda,\mu}(\theta \circ f) = \text{Var}_{\mathbf{X}_\lambda,\mu}(f^*\pi^*\theta(\mathbf{X}_\lambda)).$$

Since θ is closed, $f^*\pi^*\theta$ is a closed 1-form in SM . Observe that $\text{Var}_{\mathbf{X}_\lambda,\mu}(f^*\pi^*\theta(\mathbf{X}_\lambda))$ only depends on the cohomology class $[f^*\pi^*\theta]$ since the variance vanishes on coboundaries. We noted before that f is isotopic to the identity, thus

$$\begin{aligned} \text{Var}_{\mathbf{X}_\lambda,\mu}(f^*\pi^*\theta(\mathbf{X}_\lambda)) &= \text{Var}_{\mathbf{X}_\lambda,\mu}(\pi^*\theta(\mathbf{X}_\lambda)) = \text{Var}_{\mathbf{X}_\lambda,\mu}(\sqrt{1 - \lambda^2} \theta) \\ &= (1 - \lambda^2) \text{Var}_{\mathbf{X}_\lambda,\mu}(\theta). \end{aligned}$$

From the definition of the variance it follows right away that if $F : SM \rightarrow \mathbb{R}$ is any function then

$$\text{Var}_{\mathbf{X}_\lambda,\mu}(F) = \sqrt{1 - \lambda^2} \text{Var}_\mu(F)$$

which yields

$$\text{Var}_{\mathbf{X}_\lambda,\mu}(f^*\pi^*\theta(\mathbf{X}_\lambda)) = (1 - \lambda^2)^{3/2} \text{Var}_\mu(\theta).$$

Summarizing

$$\text{Var}_{\lambda,\mu}(\theta) = (1 - \lambda^2)^{3/2} \text{Var}_\mu(\theta).$$

Thus we have obtained the following formula for the second derivative of entropy production in the presence of a uniform magnetic field with intensity λ :

$$e_\lambda''(0) = (1 - \lambda^2)^{3/2} \frac{2}{\text{Vol}(M)} \int_M |\theta|^2.$$

A completely analogous formula can be obtained for compact quotients of complex hyperbolic space with magnetic field given by the Kähler 2-form.

3. NON-PERTURBATIVE RESULTS

All the results in this section will be based on studying the cohomological equation using Pestov type identities. The results on the cohomological equation are all collected in Sec. 4.

3.1. Axiom A Thermostats

A closed ϕ -invariant set Λ is said to be hyperbolic if $T(SM)$ restricted to Λ splits as $T_\Lambda(SM) = \mathbb{R}\mathbf{G}_E \oplus E^u \oplus E^s$ in such a way that there are constants $C > 0$ and $0 < \rho < 1 < \eta$ such that for all $t > 0$ we have

$$\|d\phi_{-t}|_{E^u}\| \leq C \eta^{-t} \quad \text{and} \quad \|d\phi_t|_{E^s}\| \leq C \rho^t.$$

The flow is Axiom A if the nonwandering set Ω is hyperbolic and the closed orbits are dense in Ω . Recall that by the Smale spectral decomposition, Ω is a finite union of disjoint *basic* hyperbolic sets. A hyperbolic basic set is a hyperbolic set such that:

- the periodic orbits of $\phi|_\Lambda$ are dense in Λ ;
- $\phi|_\Lambda$ is transitive;
- there is an open set $U \supset \Lambda$ such that $\bigcap_{t \in \mathbb{R}} \phi_t(U) = \Lambda$.

The flow ϕ is Anosov if SM is a hyperbolic set. If ϕ is Anosov, it is also Axiom A (but not conversely, of course). Recall that there are examples of Anosov flows for which Ω is not the whole space.⁽⁹⁾

Lemma 3.1. *Let ϕ be an Axiom A thermostat and ρ an SRB state. If $e_\rho(\phi) = 0$, then ϕ is a transitive Anosov flow and there exists a smooth solution u of $\mathbf{G}_E(u) = \theta$.*

Proof: Let Λ be the basic hyperbolic set on which ρ is supported. Since ρ is an SRB measure, [Ref. 2, Theorem 5.6] implies that Λ is an attractor, that is, there exists an open set $U \supset \Lambda$ such that $\Lambda = \bigcap_{t \geq 0} \phi_t(U)$.

As pointed out in the introduction, if $e_\rho(\phi) = 0$, then

$$\begin{aligned} h_\rho(\phi) &= \sum \text{positive Lyapunov exponents} \\ &= - \sum \text{negative Lyapunov exponents.} \end{aligned}$$

Thus ρ is an SRB measure for both ϕ_t and ϕ_{-t} . Consequently, Λ is an attractor for both ϕ_t and ϕ_{-t} . This forces Λ to be open and since it is closed, $\Lambda = SM$ and ϕ is a transitive Anosov flow.

Let J_t^s and J_t^u be the stable and unstable Jacobians of ϕ . If ρ is an SRB measure for both ϕ_t and ϕ_{-t} then the theory of Gibbs states for transitive Anosov flows (cf. Ref. 19, Proposition 20.3.10) implies that $-\frac{d}{dt}|_{t=0} \log J_t^u$ and $\frac{d}{dt}|_{t=0} \log J_t^s$ are cohomologous (and the coboundary is the derivative along the flow of a Hölder continuous function). It follows that ϕ preserves an absolutely continuous invariant measure with positive continuous density (and this measure would have to be ρ). An application of the smooth Livšic theorem [Ref. 21, Corollary 2.1] shows that ϕ preserves an absolutely continuous invariant measure with positive

continuous density if and only if ϕ preserves a smooth volume form. But if ϕ preserves a smooth volume form, then there is a smooth solution u of $\mathbf{G}_E(u) = \theta$ as desired. \square

3.2. Proof of Theorem B

We are required to prove that if $e_\rho(\phi) = 0$, then E has a global potential. By [Ref. 37, Theorem 5.1] the condition $k < 0$ implies that ϕ is Anosov and hence Axiom A. By Lemma 3.1, there is a smooth solution u of $\mathbf{G}_E(u) = \theta$. Theorem 4.4 implies that θ is exact as desired.

3.3. Proof of Theorem C

We will need some preliminaries which can all be found in Ref. 17. Let $L^2(SM)$ be the space of square integrable functions with respect to the Liouville measure of SM . The space $L^2(SM)$ decomposes into an orthogonal direct sum of subspaces $\sum H_n$, $n \in \mathbb{Z}$, such that on H_n , $-iV$ is n times the identity operator. Consider the following first order differential operator:

$$\eta_- := (\mathbf{G} + iH)/2.$$

The operator η_- extends to a densely defined operator from H_n to H_{n-1} for all n . If we let $C_n^\infty(SM) = H_n \cap C^\infty(SM)$, then $\eta_- : C_n^\infty \rightarrow C_{n-1}^\infty$ is a first order elliptic differential operator. The kernel of the elliptic operator η_- in $C_k^\infty(SM)$ is a finite dimensional vector space which can be identified with \mathcal{H}_k . (For all these properties see Ref. 17.)

Now take $q \in \mathcal{H}_k$ and let $\lambda := \Re(q)$. Then $p := V(\lambda) = \Re(ikq)$. Since $\eta_-q = 0$, we see right away that $\mathbf{G}(p) + HV(p)/k = 0$ and hence Theorem 4.6 implies that $V(\lambda)$ is a coboundary iff $\lambda = 0$. But $V(\lambda)$ is the divergence of the generalized thermostat with respect to Θ (cf. Ref. 6, Lemma 3.2), so the entropy production vanishes iff $\lambda = 0$ as desired.

4. PESTOV IDENTITY AND COHOMOLOGICAL EQUATION FOR THERMOSTATS

4.1. Semibasic Tensor Fields

Let $\pi : TM \setminus \{0\} \rightarrow M$ be the natural projection, and let $\beta_s^r M := \pi^* \tau_s^r M$ denote the bundle of semibasic tensors of degree (r, s) , where $\tau_s^r M$ is the bundle of tensors of degree (r, s) over M . Sections of the bundles $\beta_s^r M$ are called semibasic tensor fields and the space of all smooth sections is denoted by $C^\infty(\beta_s^r M)$. For such a field T , the coordinate representation

$$T = (T_{j_1 \dots j_s}^{i_1 \dots i_r})(x, y)$$

holds in the domain of a standard local coordinate system (x^i, y^i) on $TM \setminus \{0\}$ associated with a local coordinate system (x^i) in M . Under a change of a local coordinate system, the components of a semibasic tensor field are transformed by the same formula as those of an ordinary tensor field on M .

Every “ordinary” tensor field on M defines a semibasic tensor field by the rule $T \mapsto T \circ \pi$, so that the space of tensor fields on M can be treated as embedded in the space of semibasic tensor fields.

For a semibasic tensor field $(T_{j_1 \dots j_s}^{i_1 \dots i_r})(x, y)$, the horizontal derivative is defined by

$$T_{j_1 \dots j_s | k}^{i_1 \dots i_r} = \frac{\partial}{\partial x^k} T_{j_1 \dots j_s}^{i_1 \dots i_r} - \Gamma_{kq}^p y^q \frac{\partial}{\partial y^p} T_{j_1 \dots j_s}^{i_1 \dots i_r} + \sum_{m=1}^r \Gamma_{kp}^{i_m} T_{j_1 \dots j_s}^{i_1 \dots i_{m-1} p i_{m+1} \dots i_r} - \sum_{m=1}^r \Gamma_{kj_m}^p T_{j_1 \dots j_{m-1} p j_{m+1} \dots j_s}^{i_1 \dots i_r},$$

and the vertical derivative by

$$T_{j_1 \dots j_s, k}^{i_1 \dots i_r} = \frac{\partial}{\partial y^k} T_{j_1 \dots j_s}^{i_1 \dots i_r}.$$

The operators

$$\nabla_{\perp} : C^{\infty}(\beta_s^r M) \rightarrow C^{\infty}(\beta_{s+1}^r M) \quad \text{and} \quad \nabla_{\cdot} : C^{\infty}(\beta_s^r M) \rightarrow C^{\infty}(\beta_{s+1}^r M)$$

are defined as

$$(\nabla_{\perp} T)_{j_1 \dots j_s}^{i_1 \dots i_r} = \nabla_{|k} T_{j_1 \dots j_s}^{i_1 \dots i_r} := T_{j_1 \dots j_s | k}^{i_1 \dots i_r} \quad \text{and} \quad (\nabla_{\cdot} T)_{j_1 \dots j_s, k}^{i_1 \dots i_r} = \nabla_{\cdot k} T_{j_1 \dots j_s}^{i_1 \dots i_r} = T_{j_1 \dots j_s, k}^{i_1 \dots i_r}.$$

In Refs. 24, 33, the operators ∇_{\perp} and ∇_{\cdot} were denoted by $\frac{h}{\nabla}$ and $\frac{v}{\nabla}$ respectively.

4.2. Thermostats and the Modified Horizontal Derivative

Let (M, g) be a closed connected Riemannian manifold. Given a vector field E on M , define $Y \in C^{\infty}(\beta_1^1 M)$ by

$$Y_{(x,y)}(\cdot) = \frac{1}{|y|^2} (\langle y, \cdot \rangle E_x - \langle E_x, \cdot \rangle y).$$

We have seen that the equation

$$\frac{D\dot{\gamma}}{dt} = Y_{(\dot{\gamma}, \dot{\gamma})}(\dot{\gamma}) \tag{8}$$

defines the Gaussian thermostat on SM .

Since the flow on SM defined by (8) depends only on the restriction of Y to SM , we may redefine Y to be

$$Y_{(x,y)}(\cdot) = \langle y, \cdot \rangle E_x - \langle E_x, \cdot \rangle y$$

without changing the flow on SM , so that from now on

$$Y_j^i(x, y) = y_j E^i(x) - E_j(x) y^i.$$

Given $T = (T_{j_1 \dots j_s}^{i_1 \dots i_r}) \in C^\infty(\beta_s^r M)$, we define the modified horizontal derivative as:

$$T_{j_1 \dots j_s; k}^{i_1 \dots i_r} = T_{j_1 \dots j_s | k}^{i_1 \dots i_r} + T_{j_1 \dots j_s; j}^{i_1 \dots i_r} Y_k^j,$$

so that $\nabla : C^\infty(\beta_s^r M) \rightarrow C^\infty(\beta_{s+1}^r M)$.

For convenience, we also define $\nabla^|$, $\nabla^.$, and $\nabla^:$ as

$$\nabla^{|i} = g^{ij} \nabla_{|j}, \quad \nabla^{.i} = g^{ij} \nabla_{.j}, \quad \nabla^{:i} = g^{ij} \nabla_{:j}.$$

We also set

$$\mathbf{X}T_{j_1 \dots j_s}^{i_1 \dots i_r} = y^k T_{j_1 \dots j_s; k}^{i_1 \dots i_r}.$$

In particular, if $u \in C^\infty(TM \setminus \{0\})$, then

$$\mathbf{X}u = y^i u_{.i} = y^i (u_{|i} + Y_i^j u_{.j}).$$

Note that \mathbf{X} restricted to SM coincides with \mathbf{G}_E .

It easy to see that if γ satisfies (8), then

$$(\mathbf{X}T)(\gamma, \dot{\gamma}) = \frac{D}{dt}(T(\gamma, \dot{\gamma})).$$

Straightforward calculations give:

$$Y_{j|k}^i = y_j E_{.k}^i - E_{j.k} y^i \tag{9}$$

$$Y_{j.k}^i = g_{jk} E^i - E_j \delta_k^i, \tag{10}$$

$$y_{.k}^i = Y_k^i = y_k E^i - E_k y^i, \tag{11}$$

where (y^j) stands for the semibasic vector field $(x, y) \mapsto (y^j)$.

For $V = (V^i) \in C^\infty(\beta_0^1 M)$, we set

$$\overset{h}{\text{div}} V := V_{|i}^i, \quad \overset{v}{\text{div}} V := V_{.i}^i, \quad \overset{m}{\text{div}} V := V_{:i}^i.$$

We recall the Gauss–Ostrogradskii formulas for the horizontal and vertical divergences⁽³³⁾ (see also Ref. 7, Sec. 4.2, which deals with the case of Finsler metrics). If $V(x, y)$ is a smooth semibasic vector field positively homogeneous of

degree λ in y , then

$$\int_{SM} \overset{h}{\operatorname{div}} V \, d\mu = 0, \tag{12}$$

$$\int_{SM} \overset{v}{\operatorname{div}} V \, d\mu = \int_{SM} (\lambda + n - 1) \langle V, y \rangle \, d\mu, \tag{13}$$

where $d\mu$ is the Liouville measure on SM . Whence we also have

$$\int_{SM} \overset{m}{\operatorname{div}} V \, d\mu = (\lambda + n) \int_{SM} \langle E, y \rangle \langle V, y \rangle \, d\mu - (\lambda + 1) \int_{SM} \langle V, E \rangle \, d\mu, \tag{14}$$

because

$$\overset{m}{\operatorname{div}} V = V_{:k}^k = V_{|k}^k + V_{:i}^k (y_k E^i - E_k y^i) = \overset{h}{\operatorname{div}} V + \overset{v}{\operatorname{div}} (\langle V, y \rangle E) - (\lambda + 1) \langle V, E \rangle.$$

4.3. Pestov Identity

Given a function $u : SM \rightarrow \mathbb{R}$, we will also denote by u its extension to a positively homogeneous function on $TM \setminus \{0\}$ (hoping that this will not yield any confusion).

We first recall commutation formulas for horizontal and vertical derivatives⁽³³⁾ (see also Ref. 7, Lemma 4.1, which deals with the case of Finsler metrics). If $u \in C^\infty(TM \setminus \{0\})$, then

$$u_{:l.k} - u_{:k.l} = 0, \tag{15}$$

$$u_{|l.k} - u_{:k|l} = 0, \tag{16}$$

$$u_{|l|k} - u_{|k|l} = R_{lk}^i u_{:i}, \tag{17}$$

where $R_{lk}^i = y^j R_{jlk}^i$ and R is the Riemann curvature tensor.

The next lemma is an analog of [Ref. 7, Lemma 4.5].

Lemma 4.1. *If $u \in C^\infty(TM \setminus \{0\})$, then*

$$u_{:l.k} - u_{:k.l} = (g_{lk} E^i - E_l \delta_k^i) u_{:i}, \tag{18}$$

$$u_{:l.k} - u_{:k.l} = \tilde{R}_{lk}^i u_{:i}, \tag{19}$$

with

$$\tilde{R}_{lk}^i = R_{kl}^i + (Y_{k|l}^i - Y_{l|k}^i) + (Y_k^j Y_{l:j}^i - Y_l^j Y_{k:j}^i).$$

Proof: We have

$$u_{:l.k} = (u_{|l} + Y_l^i u_{:i})_{:k} = u_{|l.k} + Y_{l:k}^i u_{:i} + Y_l^i u_{:i.k},$$

whereas

$$u_{:k:l} = u_{:k|l} + Y_l^i u_{:k:i}.$$

Thus,

$$u_{:l:k} - u_{:k:l} = (u_{|l:k} - u_{:k|l}) + Y_{l:k}^i u_{:i} + Y_l^j (u_{:i:k} - u_{:k:i}).$$

Using (15), (16), and (10), we come to (18).

Further,

$$\begin{aligned} u_{:l:k} &= u_{:l|k} + Y_k^j u_{:l;j} = (u_{|l} + Y_l^j u_{:j})_{|k} + Y_k^j (u_{|l} + Y_l^s u_{:s})_{:j} \\ &= u_{|l|k} + Y_{l|k}^j u_{:j} + Y_l^j u_{:j|k} + Y_k^j u_{|l;j} \\ &\quad + Y_k^j Y_{l;j}^s u_{:s} + Y_k^j Y_l^s u_{:s;j}. \end{aligned}$$

Therefore,

$$\begin{aligned} u_{:l:k} - u_{:k:l} &= (u_{|l|k} - u_{|k|l}) + (Y_{l|k}^j - Y_{k|l}^j) u_{:j} + Y_l^j (u_{:j|k} - u_{|k;j}) \\ &\quad + Y_k^j (u_{|l;j} - u_{:j|l}) + (Y_k^j Y_{l;j}^s - Y_l^j Y_{k;j}^s) u_{:s} + (Y_k^j Y_l^s - Y_l^j Y_k^s) u_{:s;j}. \end{aligned}$$

In view of (16), renaming indices and regrouping, we come to (19). \square

The next lemma shows a Pestov type identity for thermostats.

Lemma 4.2. *If $u \in C^\infty(TM \setminus \{0\})$ is homogeneous of degree 0 in y , then the following holds on SM :*

$$\begin{aligned} 2\langle \nabla^i u, \nabla^i (\mathbf{X}u) \rangle &= |\nabla^i u|^2 + \mathbf{X}(\langle \nabla^i u, \nabla^i u \rangle) - \operatorname{div}^v((\mathbf{X}u)\nabla^i u) + \operatorname{div}^v((\mathbf{X}u)\nabla^i u) \\ &\quad - \langle \tilde{\mathbf{R}}_y(\nabla^i u), \nabla^i u \rangle - \langle E, y \rangle \langle \nabla^i u, \nabla^i u \rangle \\ &\quad - (n-1)(\mathbf{X}u)\langle E, \nabla^i u \rangle. \end{aligned} \tag{20}$$

Proof: With the above notations, we can write

$$\mathbf{X}u = y^i u_{:i}.$$

Therefore,

$$\begin{aligned} 2\langle \nabla^i (\mathbf{X}u), \nabla^i u \rangle - \operatorname{div}^v((\mathbf{X}u)\nabla^i u) &= 2g^{ij}(\mathbf{X}u)_{:i} u_{:j} - ((\mathbf{X}u)g^{ij} u_{:j})_{:i} \\ &= g^{ij}(\mathbf{X}u)_{:i} u_{:j} - (\mathbf{X}u)g^{ij} u_{:j;i} = I - II. \end{aligned} \tag{21}$$

We rewrite the first term on the right-hand side of (21) as follows:

$$\begin{aligned} I &= g^{ij}(y^k u_{\cdot k})_{\cdot i} u_{\cdot j} = g^{ij}(u_{\cdot i} + y^k u_{\cdot k \cdot i}) u_{\cdot j} \\ &= g^{ij} u_{\cdot i} u_{\cdot j} + g^{ij} y^k [u_{\cdot i \cdot k} + (u_{\cdot k \cdot i} - u_{\cdot i \cdot k})] u_{\cdot j} \\ &= |\nabla \cdot u|^2 + y^k (g^{ij} u_{\cdot i} u_{\cdot j})_{\cdot k} - y^k g^{ij} u_{\cdot i} u_{\cdot j \cdot k} + g^{ij} y^k (g_{ki} E^m - E_k \delta_i^m) u_{\cdot m} u_{\cdot j}. \end{aligned}$$

Next

$$\begin{aligned} y^k (g^{ij} u_{\cdot i} u_{\cdot j})_{\cdot k} &= \mathbf{X}(\langle \nabla \cdot u, \nabla \cdot u \rangle), \\ y^k g^{ij} u_{\cdot i} u_{\cdot j \cdot k} &= y^k g^{ij} u_{\cdot i} [u_{\cdot k \cdot j} + (u_{\cdot j \cdot k} - u_{\cdot k \cdot j})] \\ &= g^{ij} u_{\cdot i} (y^k u_{\cdot k})_{\cdot j} - g^{ij} u_{\cdot i} y_{\cdot j}^k u_{\cdot k} + y^k g^{ij} u_{\cdot i} \tilde{\mathbf{R}}_{jk}^m u_{\cdot m} \\ &= \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle + (\mathbf{X}u) \langle E, \nabla \cdot u \rangle + \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle \end{aligned}$$

because

$$g^{ij} u_{\cdot i} y_{\cdot j}^k u_{\cdot k} = g^{ij} u_{\cdot i} Y_j^k u_{\cdot k} = y^i u_{\cdot i} E^k u_{\cdot k} - E^i u_{\cdot i} y^k u_{\cdot k} = -(\mathbf{X}u) \langle E, \nabla \cdot u \rangle,$$

and

$$\begin{aligned} g^{ij} y^k (g_{ki} E^m - E_k \delta_i^m) u_{\cdot m} u_{\cdot j} &= y^j E^m u_{\cdot m} u_{\cdot j} - g^{ij} y^k E_k u_{\cdot i} u_{\cdot j} \\ &= (\mathbf{X}u) \langle E, \nabla \cdot u \rangle - \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle. \end{aligned}$$

Thus,

$$\begin{aligned} I &= |\nabla \cdot u|^2 + \mathbf{X}(\langle \nabla \cdot u, \nabla \cdot u \rangle) - \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle \\ &\quad - \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle - \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle. \end{aligned} \quad (22)$$

We rewrite the second term on the right-hand side of (21) as

$$\begin{aligned} II &= (\mathbf{X}u) g^{ij} u_{\cdot j \cdot i} = (\mathbf{X}u) g^{ij} [u_{\cdot i \cdot j} + (u_{\cdot j \cdot i} - u_{\cdot i \cdot j})] \\ &= [(\mathbf{X}u) g^{ij} u_{\cdot i}]_{\cdot j} - (\mathbf{X}u)_{\cdot j} g^{ij} u_{\cdot i} + (\mathbf{X}u) g^{ij} (g_{ji} E^m - E_j \delta_i^m) u_{\cdot m}. \end{aligned}$$

Note that

$$[(\mathbf{X}u) g^{ij} u_{\cdot i}]_{\cdot j} = \operatorname{div}^m((\mathbf{X}u) \nabla \cdot u),$$

that

$$(\mathbf{X}u)_{\cdot j} g^{ij} u_{\cdot i} = \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle,$$

and that

$$(\mathbf{X}u) g^{ij} (g_{ji} E^m - E_j \delta_i^m) u_{\cdot m} = (n-1)(\mathbf{X}u) \langle E, \nabla \cdot u \rangle.$$

Thus,

$$II = \operatorname{div}^m((\mathbf{X}u) \nabla \cdot u) - \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle + (n-1)(\mathbf{X}u) \langle E, \nabla \cdot u \rangle. \quad (23)$$

Inserting (22)–(23) in (21), we come to (20). \square

Note that for the curvature term in (20) we have, putting $Z = \nabla \cdot u$:

$$\langle \tilde{\mathbf{R}}_y(Z), Z \rangle = \langle \mathbf{R}_y(Z), Z \rangle - \langle \nabla_Z E, Z \rangle - \langle E, Z \rangle^2. \quad (24)$$

Indeed,

$$\begin{aligned} \langle \tilde{\mathbf{R}}_y(Z), Z \rangle &= [R_{kl}^i + (Y_{k|l}^i - Y_{l|k}^i) + (Y_k^j Y_{l,j}^i - Y_l^j Y_{k,j}^i)] y^l Z^k Z_i \\ &= \langle \mathbf{R}_y(Z), Z \rangle + (y_k E_{,l}^i - E_{k,l} y^i - y_l E_{,k}^i + E_{l,k} y^i) y^l Z^k Z_i \\ &\quad + [(y_k E^j - E_k y^j)(g_{lj} E^i - E_l \delta_j^i) \\ &\quad - (y_l E^j - E_l y^j)(g_{kj} E^i - E_k \delta_j^i)] y^l Z^k Z_i \\ &= \langle \mathbf{R}_y(Z), Z \rangle - E_{,k}^i Z^k Z_i - E_k E_i Z^k Z^i, \end{aligned}$$

where we used the fact that $\langle Z, y \rangle = 0$ by homogeneity.

One more useful identity is:

$$\mathbf{X}(\nabla \cdot u) = \nabla \cdot (\mathbf{X}u) - \nabla \cdot u - \langle E, \nabla \cdot u \rangle y + \langle E, y \rangle \nabla \cdot u. \quad (25)$$

Indeed,

$$\begin{aligned} \mathbf{X}(u^i) &= y^k (g^{ij} u_{,j})_{,k} = y^k g^{ij} (u_{,k,j} - (u_{,k,j} - u_{,j,k})) \\ &= g^{ij} (y^k u_{,k})_{,j} - g^{ij} u_{,j} - g^{ij} y^k (g_{kj} E^m - E_k \delta_j^m) u_{,m}, \end{aligned}$$

and since

$$g^{ij} y^k (g_{kj} E^m - E_k \delta_j^m) u_{,m} = \langle E, \nabla \cdot u \rangle y^i - \langle E, y \rangle u^i,$$

we have (25).

4.4. Cohomological Equation

Suppose that the cohomological equation

$$\mathbf{G}_E u = \vartheta \quad (26)$$

holds with a smooth function u on SM and a smooth 1-form ϑ on M . Denoting the homogeneous extension of u to $TM \setminus \{0\}$ by u as before, we get

$$\mathbf{X}u(x, y) = \langle F(x), y \rangle,$$

where F is the vector field dual to ϑ with respect to the Riemannian metric.

Integrating (20) against the Liouville measure $d\mu$ and using (13), (14) yields

$$\begin{aligned} 2 \int_{SM} \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle d\mu &= \int_{SM} \{ |\nabla \cdot u|^2 + \mathbf{X}(\langle \nabla \cdot u, \nabla \cdot u \rangle) + n(\mathbf{X}u)^2 \\ &\quad - \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle - \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle \\ &\quad - (n-2)(\mathbf{X}u) \langle E, \nabla \cdot u \rangle \} d\mu. \end{aligned}$$

Note that by (2)

$$\int_{SM} \mathbf{X}(\langle \nabla \cdot u, \nabla \cdot u \rangle) d\mu = (n-1) \int_{SM} \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle d\mu.$$

Therefore,

$$\begin{aligned} 2 \int_{SM} \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle d\mu &= \int_{SM} \{ |\nabla \cdot u|^2 + n(\mathbf{X}u)^2 - \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle \\ &\quad + (n-2)[\langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle - (\mathbf{X}u)\langle E, \nabla \cdot u \rangle] \} d\mu. \end{aligned} \quad (27)$$

Using (25), we have

$$\begin{aligned} &\langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle - (\mathbf{X}u)\langle E, \nabla \cdot u \rangle \\ &= -\langle E, y \rangle \langle \nabla \cdot u, \mathbf{X}(\nabla \cdot u) \rangle + \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle \\ &\quad + \langle E, y \rangle^2 \langle \nabla \cdot u, \nabla \cdot u \rangle - (\mathbf{X}u)\langle E, \nabla \cdot u \rangle \\ &= -\langle E, y \rangle \langle \nabla \cdot u, \mathbf{X}(\nabla \cdot u) \rangle + \langle E, y \rangle^2 |\nabla \cdot u|^2 + \overset{v}{\operatorname{div}} \{ u \langle E, y \rangle \nabla \cdot (\mathbf{X}u) \} \\ &\quad - u \langle E, \nabla \cdot (\mathbf{X}u) \rangle - u \langle E, y \rangle \overset{v}{\operatorname{div}} \{ \nabla \cdot (\mathbf{X}u) \} - \overset{v}{\operatorname{div}} \{ u(\mathbf{X}u)E \} + u \langle E, \nabla \cdot (\mathbf{X}u) \rangle \\ &= -\langle E, y \rangle \langle \nabla \cdot u, \mathbf{X}(\nabla \cdot u) \rangle + \langle E, y \rangle^2 |\nabla \cdot u|^2 + \overset{v}{\operatorname{div}} \{ u \langle E, y \rangle \nabla \cdot (\mathbf{X}u) - u(\mathbf{X}u)E \} \\ &\quad - u \langle E, y \rangle \overset{v}{\operatorname{div}} \{ \nabla \cdot (\mathbf{X}u) \}. \end{aligned}$$

Plugging this in (27) and again using (13), we derive:

$$\begin{aligned} 2 \int_{SM} \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle d\mu &= \int_{SM} \{ |\nabla \cdot u|^2 + n(\mathbf{X}u)^2 - \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle \\ &\quad - (n-2)\langle E, y \rangle \langle \nabla \cdot u, \mathbf{X}(\nabla \cdot u) \rangle \\ &\quad + (n-2)\langle E, y \rangle^2 |\nabla \cdot u|^2 \} d\mu, \end{aligned} \quad (28)$$

where we used the equality $\overset{v}{\operatorname{div}}[\nabla \cdot (\mathbf{X}u)] = \overset{v}{\operatorname{div}}F = 0$.

Since

$$\int_{SM} \{ |\nabla \cdot (\mathbf{X}u)|^2 - n(\mathbf{X}u)^2 \} d\mu = \int_{SM} \{ |F|^2 - n\langle F, y \rangle^2 \} d\mu = 0,$$

we can rewrite (28) as follows, with $Z = \nabla \cdot u$:

$$\begin{aligned} 2 \int_{SM} \langle \nabla \cdot u, F \rangle d\mu &= \int_{SM} \{ |\nabla \cdot u|^2 + |F|^2 - (n-2)\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle \\ &\quad - \langle \tilde{\mathbf{R}}_y(Z), Z \rangle + (n-2)\langle E, y \rangle^2 |Z|^2 \} d\mu, \end{aligned}$$

or

$$\int_{SM} \{ |F - \nabla \cdot u|^2 - (n-2)\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle - \langle \tilde{\mathbf{R}}_y(Z), Z \rangle + (n-2)\langle E, y \rangle^2 |Z|^2 \} d\mu = 0. \quad (29)$$

From (25), we obtain

$$\langle \mathbf{X}(Z), Z \rangle = \langle F - \nabla \cdot u, Z \rangle + \langle E, y \rangle |Z|^2.$$

Fixing any real parameter α , we now rewrite (29) as follows:

$$\int_{SM} \{ |F - \nabla \cdot u|^2 - 2\alpha \langle E, y \rangle \langle F - \nabla \cdot u, Z \rangle - (n-2-2\alpha)\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle - \langle \tilde{\mathbf{R}}_y(Z), Z \rangle + (n-2-2\alpha)\langle E, y \rangle^2 |Z|^2 \} d\mu = 0,$$

or

$$\int_{SM} \{ |F - \nabla \cdot u - \alpha \langle E, y \rangle Z|^2 - (n-2-2\alpha)\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle - \langle \tilde{\mathbf{R}}_y(Z), Z \rangle + (n-2-2\alpha-\alpha^2)\langle E, y \rangle^2 |Z|^2 \} d\mu = 0. \quad (30)$$

Notice that

$$2\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle = \mathbf{X}(\langle E, y \rangle |Z|^2) - \mathbf{X}(\langle E, y \rangle) |Z|^2.$$

A direct calculation gives

$$\mathbf{X}(\langle E, y \rangle) = \langle \nabla_y E, y \rangle + |E|^2 - \langle E, y \rangle^2,$$

whence

$$2\langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle = \mathbf{X}(\langle E, y \rangle |Z|^2) - (\langle \nabla_y E, y \rangle + |E|^2 - \langle E, y \rangle^2) |Z|^2,$$

and therefore

$$\begin{aligned} 2 \int_{SM} \langle E, y \rangle \langle \mathbf{X}(Z), Z \rangle d\mu &= \int_{SM} \mathbf{X}(\langle E, y \rangle |Z|^2) d\mu \\ &\quad - \int_{SM} (\langle \nabla_y E, y \rangle + |E|^2 - \langle E, y \rangle^2) |Z|^2 d\mu \\ &= \int_{SM} \{ n\langle E, y \rangle^2 |Z|^2 - \langle \nabla_y E, y \rangle - |E|^2 \} d\mu. \end{aligned}$$

Plugging this in (30), we get

$$\int_{SM} \left\{ |F - \nabla \cdot u - \alpha \langle E, y \rangle Z|^2 + \frac{n-2-2\alpha}{2} [\langle \nabla_y E, y \rangle + |E|^2] - \langle \tilde{\mathbf{R}}_y(Z), Z \rangle - \left[\left(\frac{n-2-2\alpha}{2} \right)^2 + \left(\frac{n-2}{2} \right)^2 \right] \langle E, y \rangle^2 |Z|^2 \right\} d\mu = 0.$$

Changing $\frac{n-2-2\alpha}{2} \mapsto \alpha$ and using (24), we deduce:

$$\int_{SM} \{ |F - \nabla \cdot u - (n/2 - 1 - \alpha) \langle E, y \rangle Z|^2 + \alpha [\langle \nabla_y E, y \rangle + |E|^2] - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle + \langle E, Z \rangle^2 - [\alpha^2 + (n/2 - 1)^2] \langle E, y \rangle^2 |Z|^2 \} d\mu = 0. \tag{31}$$

So, if

$$K(\sigma_{\xi, \eta}) - \langle \nabla_{\xi} E, \xi \rangle - \alpha \langle \nabla_{\eta} E, \eta \rangle - \alpha |E|^2 - \langle E, \xi \rangle^2 + [\alpha^2 + (n/2 - 1)^2] \langle E, \eta \rangle^2 < 0$$

for every $x \in M$ and every pair of orthogonal unit vectors $\xi, \eta \in T_x M$, then $Z = 0$. This means that u is a lift to SM of a function φ on M , $u(x, y) = \varphi(x)$, and the cohomological equation implies: $\vartheta = d\varphi$. Choosing $\alpha = 1$ and putting

$$\begin{aligned} k_1(\sigma) &= K(\sigma) - \operatorname{div}_{\sigma} E - |E|^2 + [1 + (n/2 - 1)^2] |E_{\sigma}|^2, \\ &= K_w(\sigma) + \left(\frac{n}{2} - 1 \right)^2 |E_{\sigma}|^2, \end{aligned}$$

we arrive at the following:

Theorem 4.3. *Suppose $k_1 < 0$ and $\mathbf{G}_E(u) = \vartheta$. Then ϑ is exact.*

It is interesting to notice that for $n = 2$, $k_1 = K - \operatorname{div} E = K_w$, and that for $n = 3$, k_1 equals k of (5).

4.5. Using the Invariant Measure

The measure $f\mu$ is invariant if $\mathbf{G}_E(\log f) = (n - 1)\theta$. We let $u = \log f$, so that

$$\mathbf{G}_E(u) = (n - 1)\theta \tag{32}$$

and $\nu = e^u \mu$ is a flow invariant measure.

Let $V(x, y)$ be a smooth semibasic vector field positively homogeneous of degree λ in y . Since

$$e^u \overset{v}{\operatorname{div}} V = e^u V_{;i}^i = \overset{v}{\operatorname{div}}(e^u V) - \langle V, \nabla \cdot u \rangle e^u,$$

we have by (13)

$$\int_{SM} \overset{v}{\operatorname{div}} V \, dv = \int_{SM} \{(\lambda + n - 1)\langle V, y \rangle - \langle V, \nabla \cdot u \rangle\} \, dv, \quad (33)$$

and, since

$$e^u \overset{m}{\operatorname{div}} V = e^u V_{;i}^i = \overset{m}{\operatorname{div}}(e^u V) - \langle V, \nabla \cdot u \rangle e^u,$$

we have by (14)

$$\int_{SM} \overset{m}{\operatorname{div}} V \, dv = \int_{SM} \{(\lambda + n)\langle E, y \rangle \langle V, y \rangle - (\lambda + 1)\langle V, E \rangle \, dv - \langle V, \nabla \cdot u \rangle\} \, dv. \quad (34)$$

Let us integrate (20) against dv . Using the flow invariance of v together with (33) and (34) yields:

$$2 \int_{SM} \langle \nabla \cdot u, \nabla \cdot (\mathbf{X}u) \rangle \, dv = \int_{SM} \{|\nabla \cdot u|^2 + n(\mathbf{X}u)^2 - (n - 2)(\mathbf{X}u)\langle E, \nabla \cdot u \rangle - \langle E, y \rangle \langle \nabla \cdot u, \nabla \cdot u \rangle - \langle \tilde{\mathbf{R}}_y(\nabla \cdot u), \nabla \cdot u \rangle\} \, dv. \quad (35)$$

We have

$$\begin{aligned} n \int_{SM} (\mathbf{X}u)^2 \, dv &= n(n - 1)^2 \int_{SM} \langle E, y \rangle^2 e^u \, d\mu \\ &= (n - 1)^2 n \int_{SM} \langle E, y \rangle (e^u \langle E, y \rangle) \, d\mu \\ &= (n - 1)^2 \int_{SM} \overset{v}{\operatorname{div}}(e^u \langle E, y \rangle E) \, d\mu \\ &= (n - 1)^2 \int_{SM} (\langle E, y \rangle \langle \nabla \cdot u, E \rangle + |E|^2) \, dv. \end{aligned}$$

Plugging this, (24) and (32) in (35), we have, with $Z = \nabla \cdot u$:

$$\begin{aligned} 2(n - 1) \int_{SM} \langle \nabla \cdot u, E \rangle \, dv &= \int_{SM} \{|\nabla \cdot u|^2 + (n - 1)\theta \langle E, Z \rangle + (n - 1)^2 |E|^2 \\ &\quad - \theta \langle Z, \nabla \cdot u \rangle - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle \\ &\quad + \langle E, Z \rangle^2\} \, dv = 0, \end{aligned}$$

or

$$\int_{SM} \left\{ |\nabla^i u - (n - 1)E - (1/2)\theta Z|^2 - \frac{1}{4}\theta^2|Z|^2 - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle + \langle E, Z \rangle^2 \right\} dv = 0. \tag{36}$$

So, if

$$K(\sigma_{\xi, \eta}) - \langle \nabla_{\xi} E, \xi \rangle - \langle E, \xi \rangle^2 + \frac{1}{4}\langle E, \eta \rangle^2 < 0$$

for every $x \in M$ and every pair of orthogonal unit vectors $\xi, \eta \in T_x M$, then $Z = 0$. Passing by we note that this condition also implies that ϕ is Anosov by [Ref. 36, Theorem 4.1].

Using (25), we have

$$\mathbf{X}(Z) = (n - 1)E - \nabla^i u - \langle E, Z \rangle y + \theta Z. \tag{37}$$

Then we can rewrite (36) as

$$\int_{SM} \left\{ |\mathbf{X}(Z) + \langle E, Z \rangle y - (1/2)\theta Z|^2 - \frac{1}{4}\theta^2|Z|^2 - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle + \langle E, Z \rangle^2 \right\} dv = 0$$

or

$$\int_{SM} \left\{ |\mathbf{X}(Z) + \langle E, Z \rangle y + (1/2)\theta Z|^2 - 2\theta \langle \mathbf{X}(Z), Z \rangle - \frac{1}{4}\theta^2|Z|^2 - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle + \langle E, Z \rangle^2 \right\} dv = 0$$

or, using

$$2\theta \langle \mathbf{X}(Z), Z \rangle = \mathbf{X}(\theta|Z|^2) - |Z|^2 \mathbf{X}\theta = \mathbf{X}(\theta|Z|^2) - (\langle \nabla_y E, y \rangle + |E|^2 - \theta^2)|Z|^2,$$

as

$$\int_{SM} \left\{ |\mathbf{X}(Z) + \langle E, Z \rangle y + (1/2)\theta Z|^2 - \langle \mathbf{R}_y(Z), Z \rangle + \langle \nabla_Z E, Z \rangle + \langle \nabla_y E, y \rangle |Z|^2 + |E|^2 |Z|^2 - \langle E, Z \rangle^2 - \frac{5}{4}\theta^2 |Z|^2 \right\} dv = 0. \tag{38}$$

Recall that

$$k(\sigma) = K(\sigma) - \operatorname{div}_\sigma E - |E|^2 + \frac{5}{4}|E_\sigma|^2.$$

Hence if $k(\sigma) < 0$ for every x and every two-plane $\sigma \in T_x M$, (38) implies $Z = 0$ and hence we obtain:

Theorem 4.4. *Suppose $k < 0$ and $\mathbf{G}_E(u) = \theta$. Then θ is exact.*

To complete these results we now show that if the thermostat is transitive and the inequality $k(\sigma) \leq 0$ holds for all σ , then $Z = 0$. Indeed, in this case

$$K(\sigma) - \operatorname{div}_\sigma E - |E|^2 + \frac{5}{4}\langle E, \eta \rangle^2 < 0$$

unless $\langle E, \xi \rangle = 0$, where $\{\eta, \xi\}$ is an orthonormal basis of σ .

Then (38) yields

$$\langle E, Z \rangle = 0$$

and

$$\mathbf{X}Z + \langle E, Z \rangle y + (1/2)\theta Z = 0.$$

Then

$$\mathbf{X}Z = -\frac{1}{2}\theta Z,$$

yielding

$$\mathbf{X}(|Z|^2) = -\theta|Z|^2.$$

Assuming the set $\{Z \neq 0\}$ to be nonempty, we obtain on this set

$$\mathbf{X}(\log |Z|^2) = -\theta = -(\mathbf{X}u)/(n - 1).$$

Consider this equation on a dense orbit. Then

$$|Z|^2 = Ce^{-u/(n-1)}$$

on every connected component of the intersection of this orbit with the set $\{Z \neq 0\}$, with some nonzero constant C depending on the component. Such a component is obviously open in this orbit. At the same time, it is closed as the right hand side of the above equality is separated from zero. This means that the whole orbit is in the set $\{Z \neq 0\}$ and so the above holds on this orbit with the same nonzero constant, which means that $|Z|$ is separated from zero on a dense orbit, and consequently it is nonzero everywhere. We now show that this is not possible.

Recall that $\nabla u := (u^i)$ where $u^i := g^{ij}u_j$ and $u_j := \frac{\partial u}{\partial y^j}$. Fix $x_0 \in M$ and consider the restriction \tilde{u} of u to $S_{x_0}M$. Since $S_{x_0}M$ is compact there is $y_0 \in$

$S_x M$ for which $d_{y_0} \tilde{u} = 0$. Since u is homogeneous of degree zero we must have $\nabla u(x_0, y_0) = 0$.

Thus $Z = \nabla u = 0$ everywhere in SM .

Summarizing, we have proved:

Theorem 4.5. *Let ϕ be a transitive Gaussian thermostat with $k \leq 0$. Then ϕ preserves a smooth volume form if and only if E has a global potential.*

4.6. Cohomological Equation for Generalized Thermostats on Surfaces

Consider the thermostat ϕ determined by an arbitrary function $\lambda \in C^\infty(SM)$ and let \mathbf{G}_λ be its infinitesimal generator.

Theorem 4.6. *Let $p \in C^\infty(SM)$ be such that $\mathbf{G}(p) + HV(p)/k = 0$ for some positive integer k , and suppose*

$$K - H(\lambda) + \lambda^2[(k + 1)^2/(2k + 1)] \leq 0.$$

Then there exists $u \in C^\infty(SM)$ such that $\mathbf{G}_\lambda(u) = p$ if and only if $p = 0$.

Proof: Note that $\mathbf{G}_\lambda = \mathbf{G} + \lambda V$. We will use the following Pestov type integral identity proved in [Ref. 6, Equation (13)]. Given $u \in C^\infty(SM)$ we have:

$$\begin{aligned} 2 \int_{SM} Hu V \mathbf{G}_\lambda u \, d\mu &= \int_{SM} (\mathbf{G}_\lambda u)^2 \, d\mu + \int_{SM} (Hu)^2 \, d\mu \\ &\quad - \int_{SM} (K - H(\lambda) + \lambda^2)(Vu)^2 \, d\mu. \end{aligned} \tag{39}$$

Using that $\mathbf{G}(p) + HV(p)/k = 0$ and that H and \mathbf{G} preserve the Liouville measure we obtain:

$$\begin{aligned} \int_{SM} Hu V(p) \, d\mu &= - \int_{SM} u HV(p) \, d\mu \\ &= k \int_{SM} u \mathbf{G}(p) \, d\mu = -k \int_{SM} \mathbf{G}(u) p \, d\mu. \end{aligned}$$

Since $\mathbf{G}(u) = p - \lambda V(u)$ we derive

$$\int_{SM} Hu V \mathbf{G}_\lambda u \, d\mu = -k \int_{SM} p^2 \, d\mu + k \int_{SM} \lambda V(u) p \, d\mu.$$

Combining the last equality with (39) yields

$$(2k + 1) \int_{SM} p^2 d\mu - 2k \int_{SM} \lambda V(u) p d\mu + \int_{SM} (Hu)^2 d\mu - \int_{SM} (K - H(\lambda) + \lambda^2)(Vu)^2 d\mu = 0.$$

We may rewrite this equality as:

$$\int_{SM} \left(\sqrt{2k + 1} p - \frac{k\lambda V(u)}{\sqrt{2k + 1}} \right)^2 d\mu - \int_{SM} \left(K - H(\lambda) + \lambda^2 \frac{(k + 1)^2}{2k + 1} \right) (Vu)^2 d\mu + \int_{SM} (Hu)^2 d\mu = 0.$$

Combining this equality with the hypotheses we obtain $Hu = 0$. Note that

$$K - H(\lambda) + \lambda^2 \leq K - H(\lambda) + \lambda^2 [(k + 1)^2 / (2k + 1)] \leq 0.$$

Using $Hu = 0$ in (39) we obtain $\mathbf{G}_\lambda(u) = p = 0$.

□

Remark 4.7. If $p(x, v) = q_x(v, \dots, v)$ where q is a symmetric k -tensor, then the condition $\mathbf{G}(p) + HV(p)/k = 0$ is just saying that q has zero divergence. For such a p and $k = 1$ it suffices to assume that ϕ is Anosov.⁽⁶⁾ It is unknown if the Anosov hypothesis is enough for $k \geq 2$. The problem is open even for geodesic flows. We refer to⁽³⁴⁾ for partial results in this direction when $k = 2$.

5. FINAL REMARKS AND OPEN PROBLEMS

We begin with the following basic open problem (also raised by Wojtkowski in Ref. 37):

Let ϕ be an Anosov Gaussian thermostat on a closed n -manifold with $n \geq 3$. Is it true that ϕ is transitive?

When $n = 2$, a result of Ghys⁽¹⁶⁾ ensures that ϕ is topologically conjugate to the geodesic flow of a metric of constant negative curvature and thus ϕ is transitive. If the weak stable and unstable bundles of ϕ are transversal to the vertical subspace and M supports an Anosov geodesic flow, then a related result in Ref. 16 also shows that ϕ is transitive. Recall that the vertical subspace \mathcal{V} at $(x, v) \in SM$ is the kernel of $d\pi_{(x,v)} : T_{(x,v)}SM \rightarrow T_xM$. Thus it is natural to ask:

Let ϕ be an Anosov Gaussian thermostat on a closed n -manifold with $n \geq 3$. Are the weak stable and unstable bundles of ϕ always transversal to \mathcal{V} ?

For $n = 2$ this is proved in Ref. 16 but the proof requires to know *a priori* that ϕ is transitive, so both questions are intimately related.

We now make the following useful observation.

Proposition 5.1. *Let ϕ be a transitive Anosov thermostat on a closed manifold. Then ϕ is homologically full, that is, every homology class in $H_1(SM, \mathbb{Z})$ contains a closed orbit of ϕ . In particular ϕ is weak-mixing.*

Proof: We would like to use Theorem 1 in Ref. 35 which gives several equivalent conditions for a transitive Anosov flow to be homologically full. They all imply that ϕ is weak-mixing. The one that we will use is the existence of a Gibbs state μ with zero asymptotic cycle Φ_μ . As a Gibbs state we take the measure m of maximal entropy. Since an Anosov thermostat is reversible via the flip $f(x, v) = (x, -v)$ and the measure of maximal entropy is unique, we see that $f_*m = m$.

An easy argument with the Gysin sequence of the sphere bundle $\pi : SM \rightarrow M$ shows that $\pi^* : H^1(M, \mathbb{R}) \rightarrow H^1(SM, \mathbb{R})$ is an isomorphism, so given $c \in H^1(SM, \mathbb{R})$ let us write $c = [\pi^*\omega]$ where ω is a closed 1-form in M . Since $\pi^*\omega(\mathbf{G}_E) = \omega$ we have:

$$\Phi_m(c) = \int_{SM} \omega \, dm.$$

But $f_*m = m$ and $\omega \circ f = -\omega$, hence $\Phi_m(c) = 0$ for all c . □

If the 1-form θ dual to E is closed (but not exact) the results in Ref. 38 assert that ϕ is conformally symplectic and that the weak stable and unstable bundles are Lagrangian subspaces. In this case one can consider the action of $d\phi$ on the bundle of Lagrangian subspaces and using the Maslov cycle, Proposition 5.1 and arguments similar to those in [Ref. 23, Chapter 2 and Ref. 6], one can show that \mathcal{V} is transversal to the weak bundles. (Details of this will appear elsewhere.) Of course, in this case we already know that the entropy production is positive, but the transversality property may be of help in understanding the cohomological equation in general.

Besides transitivity and transversality of the weak bundles with \mathcal{V} , we may also ask:

Let ϕ be a transitive Anosov thermostat on a closed n -manifold M with $n \geq 3$. Let ϑ be a smooth 1-form on M . Suppose u is a smooth solution of

$$\mathbf{G}_E(u) = \vartheta.$$

Is it true that ϑ is exact?

For $n = 2$ this is proved in Ref. 6 and Theorem 4.3 provides an affirmative answer under certain curvature condition.

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